



# MCMC over Model Structures defined by Stochastic Logic Programs.

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# Learning distributions



Given

$D$  data

$\mathcal{M}$  set of possible models explaining the data

Fit

$\pi(M)$  probability distribution over  $\mathcal{M}$

# Bayesian learning

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## Given

$D$	data
$\mathcal{M}$	set of possible models explaining the data
$p(M)$	prior probability of a model
$L(D   M)$	likelihood of a model

## Fit

$\pi(M)$  posterior probability over  $\mathcal{M}$

$$\pi(M) = p(M|D) = \frac{L(D|M)p(M)}{\sum_M L(D|M)p(M)}$$

# MCMC for Bayesian learning

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Use MCMC to approximate normalisation factor in Bayes' theorem

$$\sum_M L(D|M)p(M)$$

## Markov chain

Construct a chain of visited models,  $M_1, M_2, \dots, M_n$ , by proposing  $M_*$  from  $M_i$ , with probability  $q(M_*, M_i)$ .  
Stochastically accept proposed model.

## Monte Carlo

Approximate the posterior  $\pi(M)$  by  $\frac{\#M_i}{\sum_k \#M_k}$

# SLP defined Cart Priors



1/3 : `cart( leaf ) .`

2/3 : `cart( node(F, V, L, R) ) :-  
 feature( F ),  
 value_of( F, V ),  
 cart( L ),  
 cart( R ) .`

1/2 : `feature( a ) .`

1/2 : `feature( b ) .`

1/2 : `value_of( _, 0 ) .`

1/2 : `value_of( _, 1 ) .`

# SLP defined Cart Priors



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```

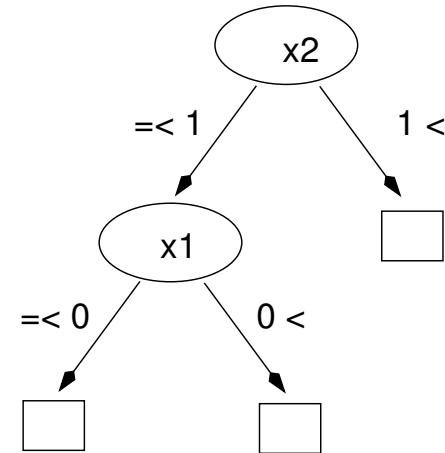
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1/2 : feature( x2 ).
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?- cart( M ).



M = node( b, 1, node( a, 0, leaf, leaf ), leaf )

# SLP defined Cart Priors



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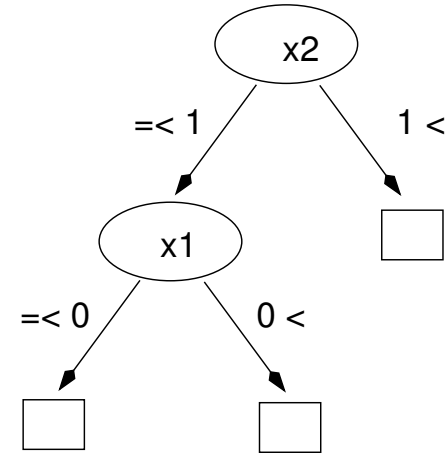
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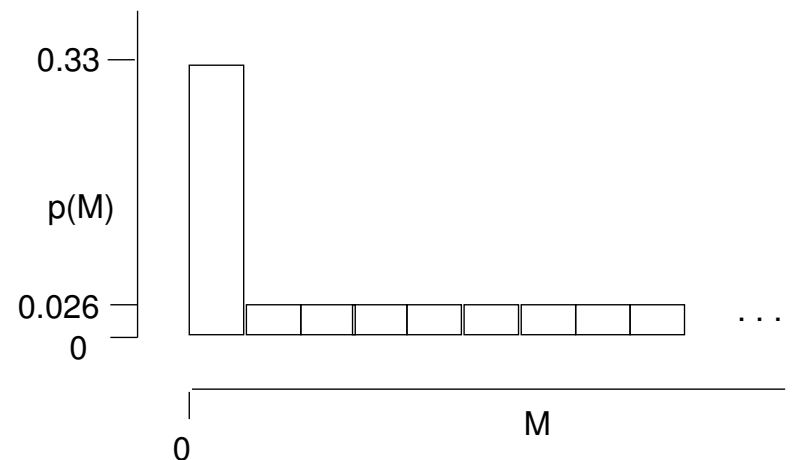
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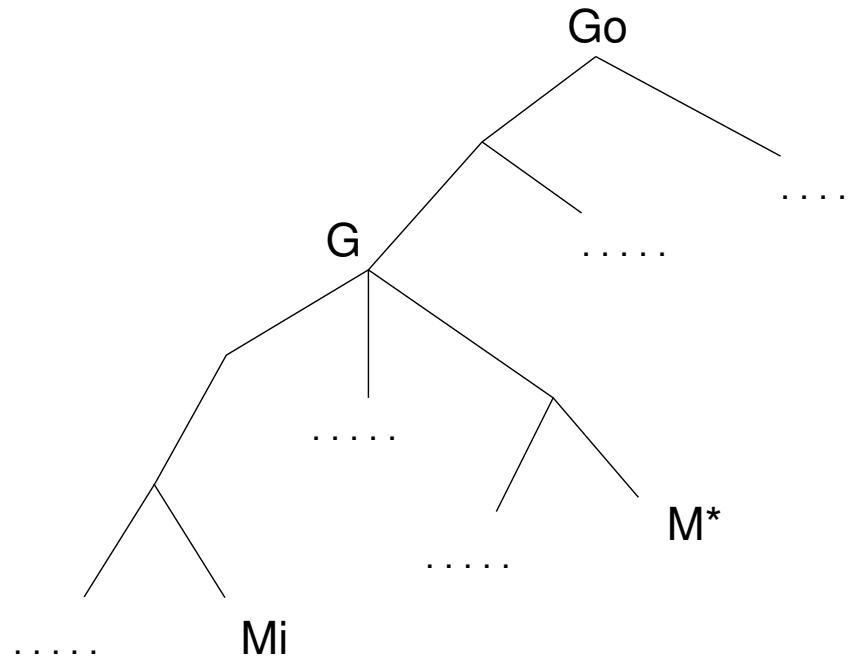
?- cart( M ).



M = node( b, 1, node(a,0,leaf,leaf), leaf )



proposal distro  $q(M_i, M_*)$





# Metropolis-Hastings

---

0. Set  $i = 0$  and find  $M_0$  using the prior.
1. From  $M_i$  produce a candidate model  $M_*$ . Let the probability of reaching  $M_*$  be  $q(M_i, M_*)$ .
2. Let

$$\alpha(M_i, M_*) = \min \left\{ \frac{q(M_*, M_i)L(D|M_*)P(M_*)}{q(M_i, M_*)L(D|M_i)P(M_i)}, 1 \right\}$$

$$M_{i+1} = \begin{cases} M_* & \text{with probability } \alpha(M_i, M_*) \\ M_i & \text{with probability } 1 - \alpha(M_i, M_*) \end{cases}$$

3. If  $i$  reached limit then terminate, else set  $i = i + 1$  and repeat from 1.

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# Cart priors - for real



Chipman et.al. :  $P_{\text{split}}(\eta) = \alpha(1 + d_{\eta})^{-\beta}$

$\alpha, \beta$ : user parameters controlling tree size

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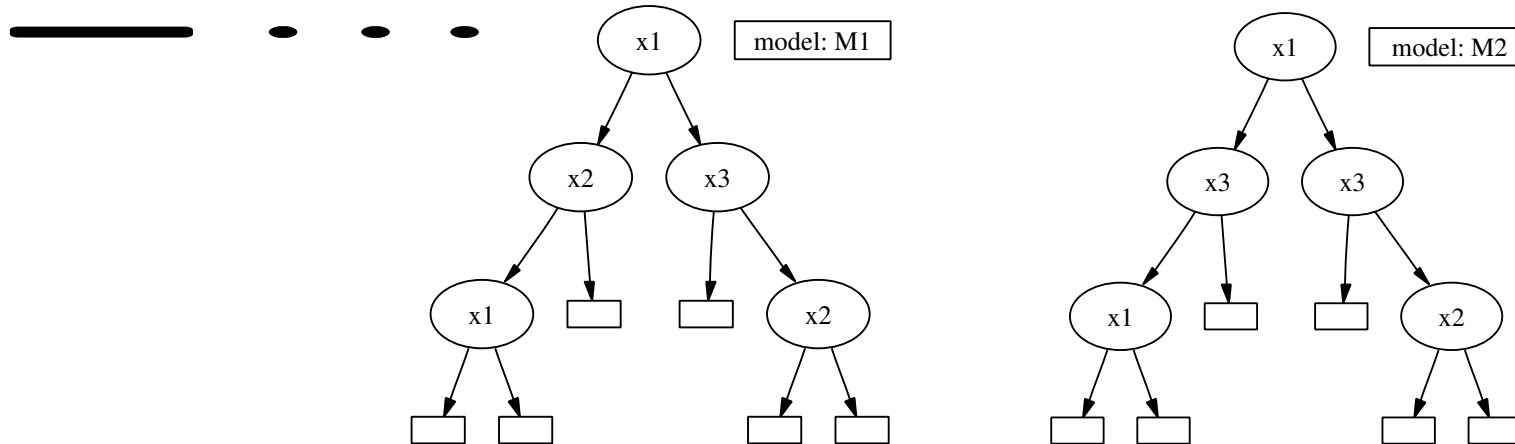


Chipman et.al. :  $P_{\text{split}}(\eta) = \alpha(1 + d_\eta)^{-\beta}$

$\alpha, \beta$ : user parameters controlling tree size

```
1 - Sp: [Sp]: cart( Data, D, A/B, leaf(Data) ).
Sp      : [Sp]: cart( Data, D, A/B, node(F, V, L, R) ) :
          branch( Data, F, V, LData, RData ),
          D1 is D + 1,
          NxtSp is A * ((1 + D1) ^ -B),
          [NxtSp] : cart( LData, D1, A/B, L ),
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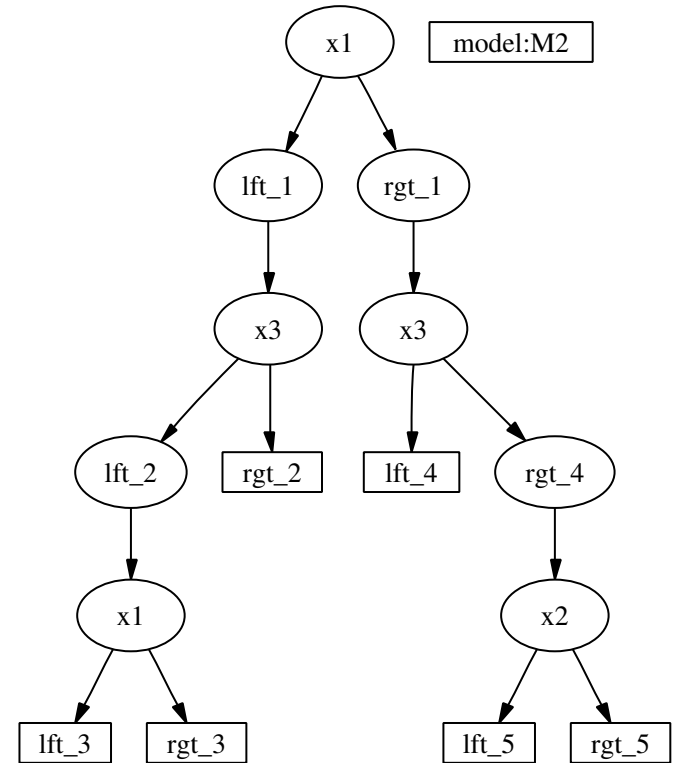
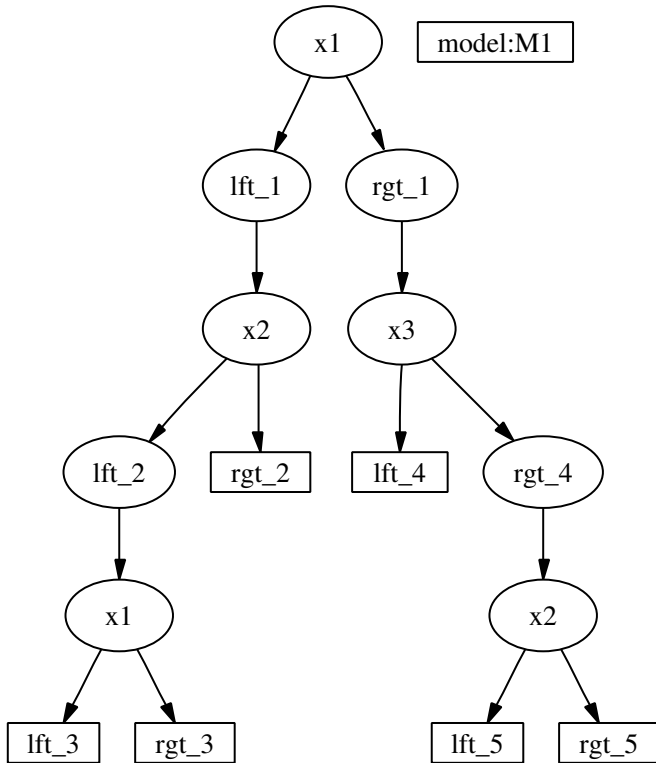
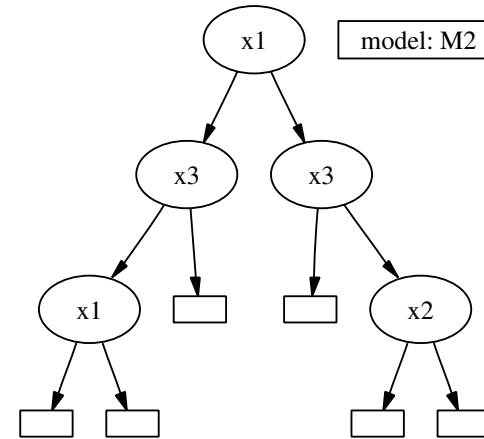
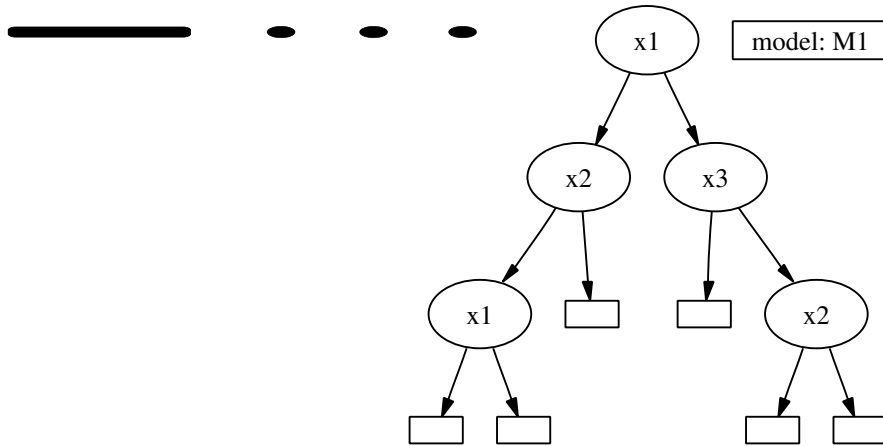
# Operations on branches



```

1 - Sp: [Sp]: cart( Data, D, A/B, leaf(Data) ).
Sp      : [Sp]: cart( Data, D, A/B, node(F,V,L,R) ) :-
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# Operations on branches

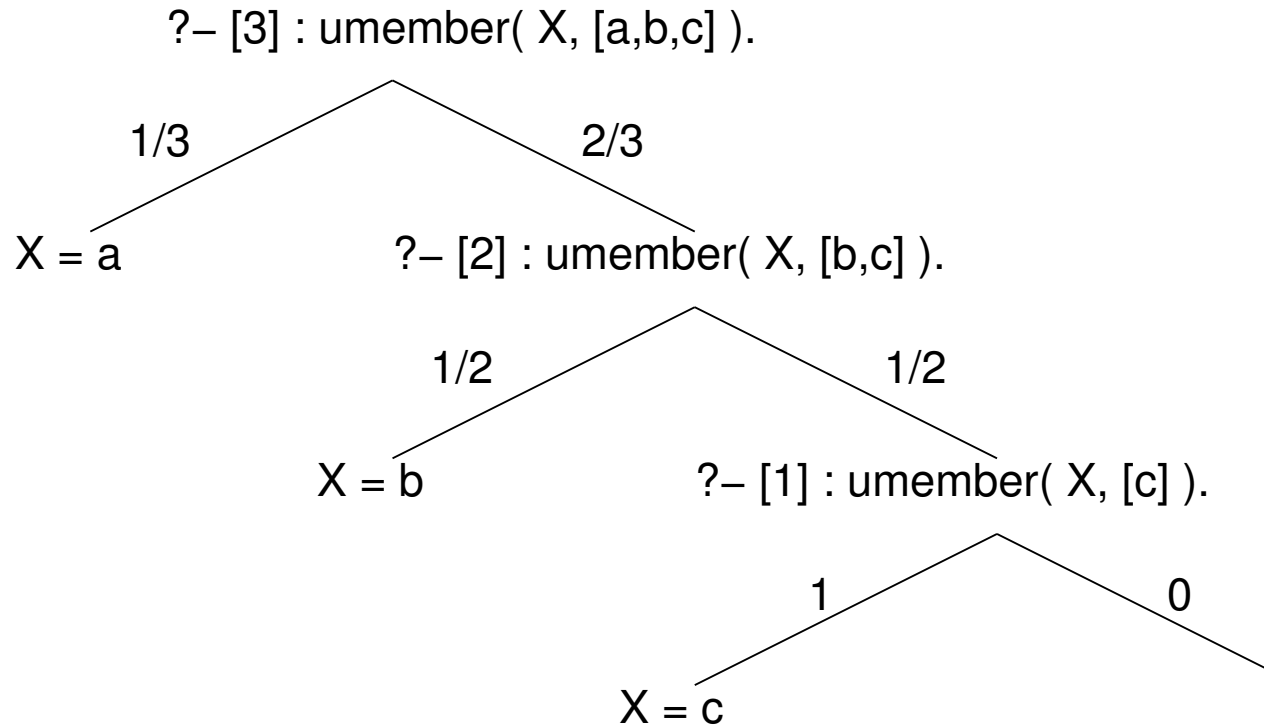


# tail recursion optimisation



```
1/L          : [L] : umember( E1, [E1|T] ).  
1 - (1/L)   : [L] : umember( E1, [_|T] ) :-  
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# tail recursion optimisation



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# Experiment

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Pima Indians Diabetes Database  
768 complete entries of 8 variables.

Denison et.al. run 250,000 iterations of local perturbations.

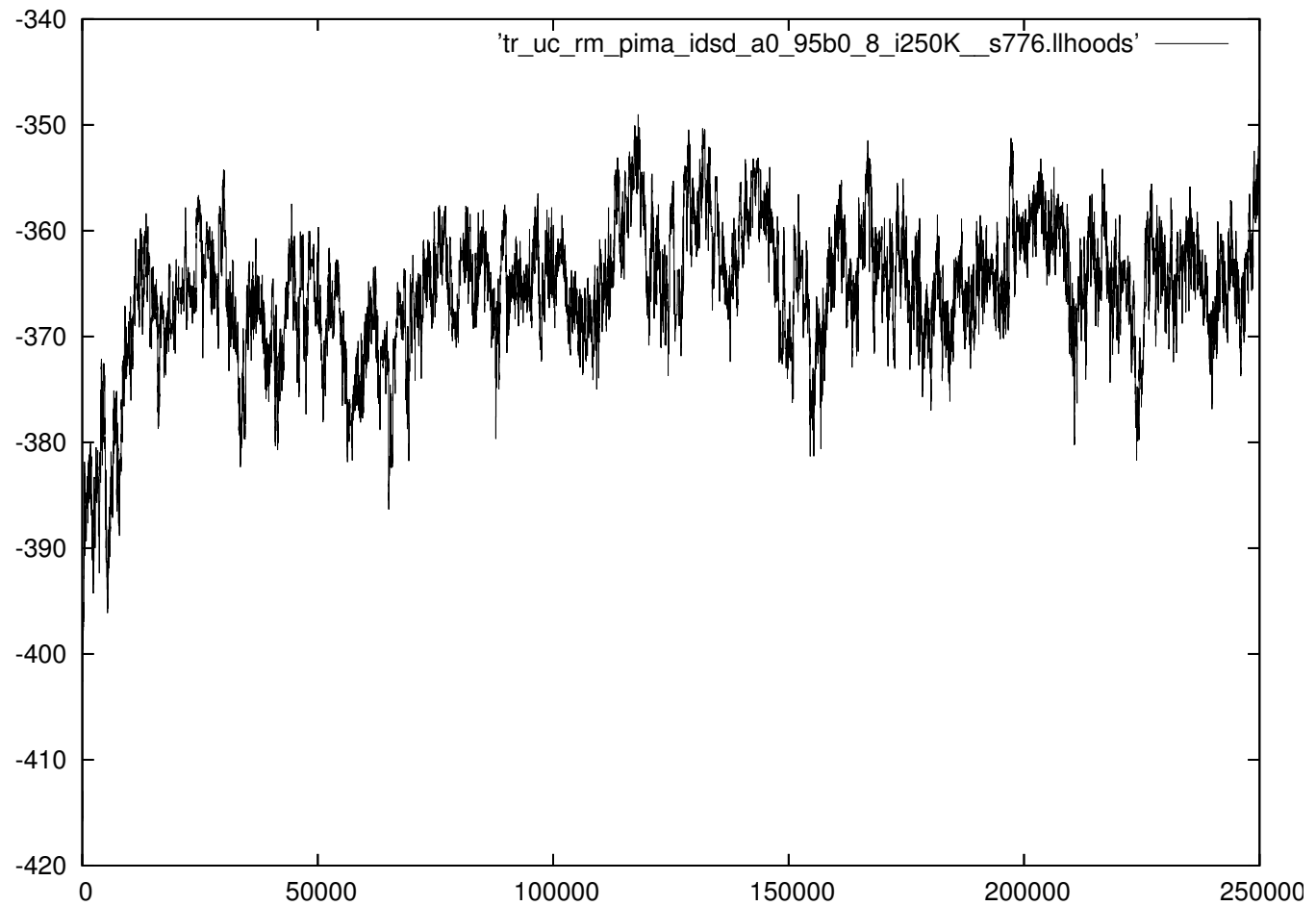
Their best likelihood model: -343.056

Our experiment run for 250,000 iterations with branch replacing.

Parameters: uniform choice proposal,  $\alpha = .95$   $\beta = .8$

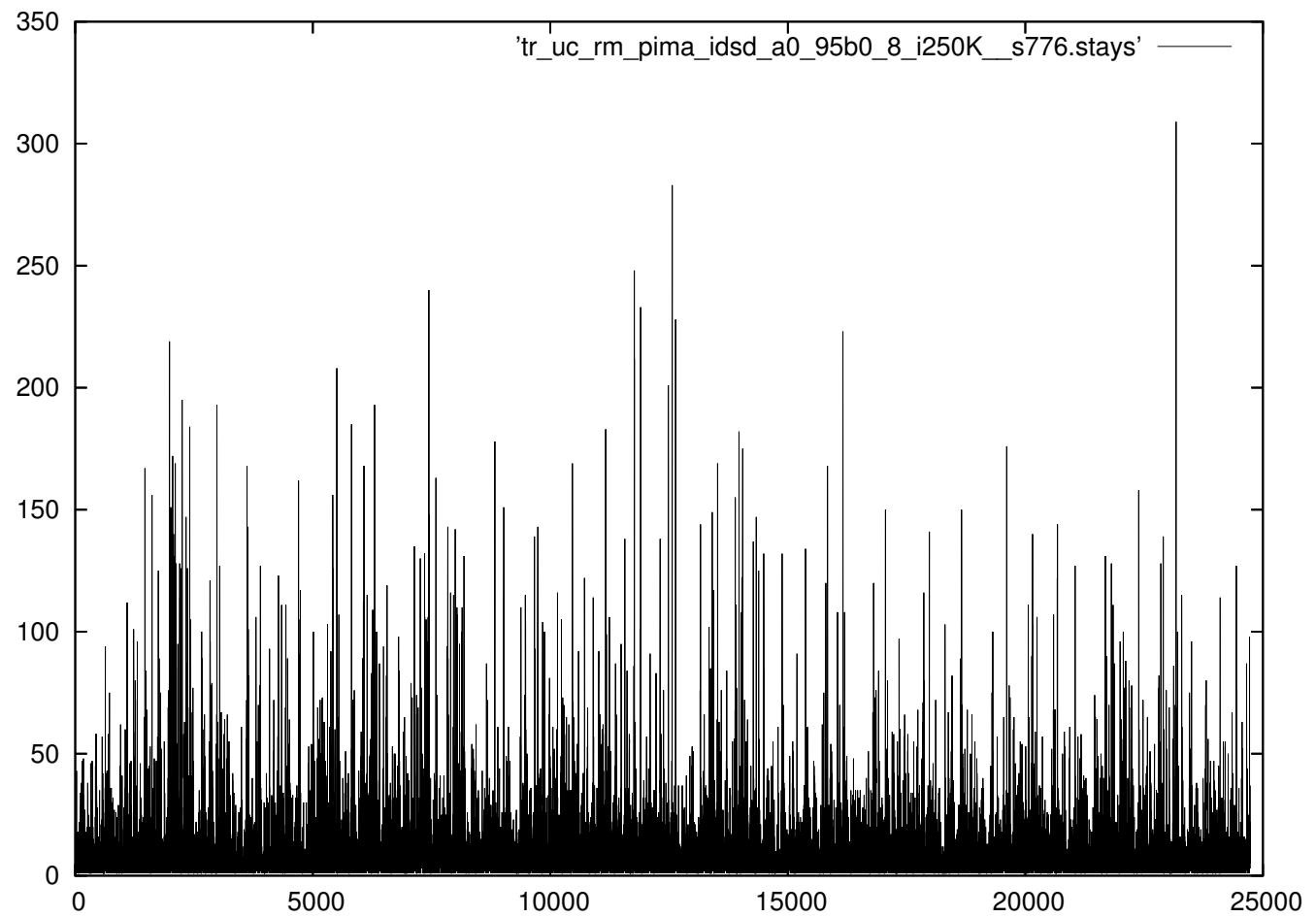
Our best likelihood model: -347.651

# Likelihoods trace

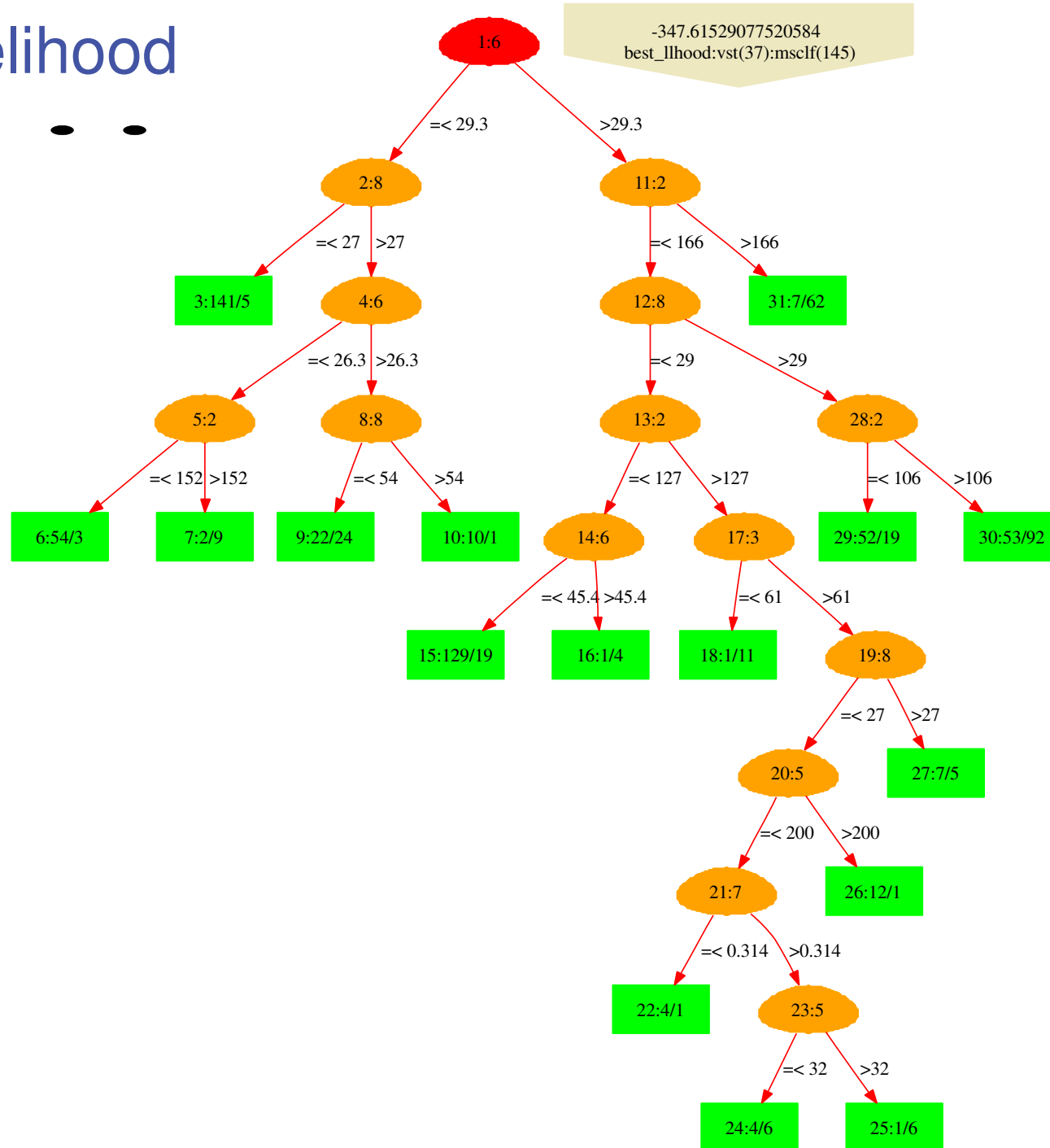


$\beta = .8, \alpha = .95, \text{proposal} = \text{uniform choice}$

# visits



# Best likelihood



## bottom line



Algorithmic reality and representational power need to work in tandem.

Software available from

<http://www.cs.york.ac.uk/~nicos/sware/slps>