



# clp(pfd(Y)) : Constraints for Probabilistic Reasoning in Logic Programming

Nicos Angelopoulos  
nicos@cs.york.ac.uk

<http://www.cs.york.ac.uk/~nicos>

Department of Computer Science  
University of York

# talk structure



- Logic Programming (LP)
- Uncertainty and LP
- Constraint LP
- clp(pfd(Y))
- clp(pfd(c))
  - Caesar's coding experiments
  - Monty Hall
- clp(pfd(bn)) -sketch

# logic programming



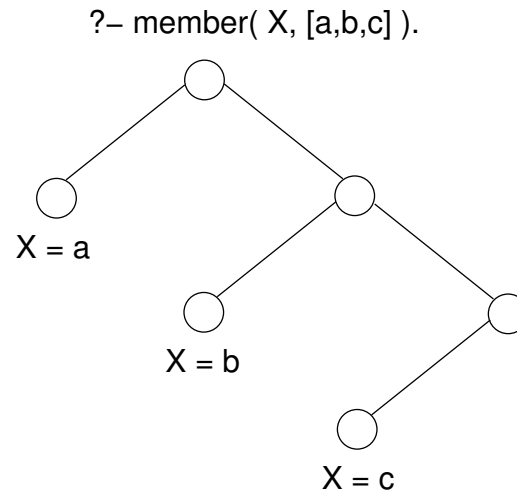
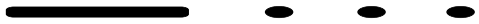
Used in AI for crisp problem solving and for building executable models and intelligent systems.

Programs are formed from logic based rules.

```
member( H, [H|T] ).
```

```
member( El, [H|T] ) :- member( El, T ).
```

# execution tree



member( H, [H|T] ).

member( EI, [H|T] ) :- member( EI, T ).

# uncertainty in logic programming



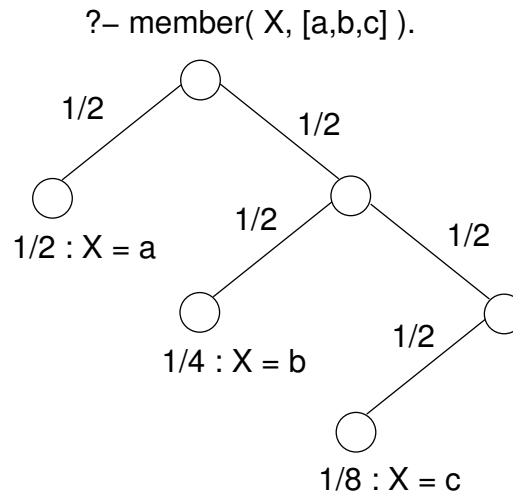
Most approaches use Probability Theory but there are fundamental questions unresolved.

For example in SLP (stochastic logic programming),

$0.5 : \text{member}( H, [H|T] ).$

$0.5 : \text{member}( EI, [H|T] ) :- \text{member}( EI, T ).$

# stochastic tree



0.5 : member( H, [H|T] ).

0.5 : member( El, [H|T] ) :- member( El, T ).

# Prism example

---

```
/* Declarations */  
target( pmember, 2 ).  
values( m(List), List ).
```

```
/* Model */  
pmember( EI, List ) :-  
    msw( m(List), EI ).
```

```
/* Utility part */  
prob_pmember( EI, List, Prob ):-  
    length( List, Length ),  
    get_uniform_param( Length, Params ),  
    set_sw( m(List), Params),  
    prob(pmember(EI, List),Prob).
```

# overloading



In these and similar formalisms both logical and statistical inference are done by a single engine.

As a result, either statistical reasoning is subordinate to logical reasoning or vice versa.



# constraints in lp



## Logic Programming :

- execution model is inflexible, and
- its relational nature discourages use of state information.

# constraints in lp



## Logic Programming :

- execution model is inflexible, and
- its relational nature discourages use of state information.

## Constraints add

- specialised algorithms

# constraints in lp



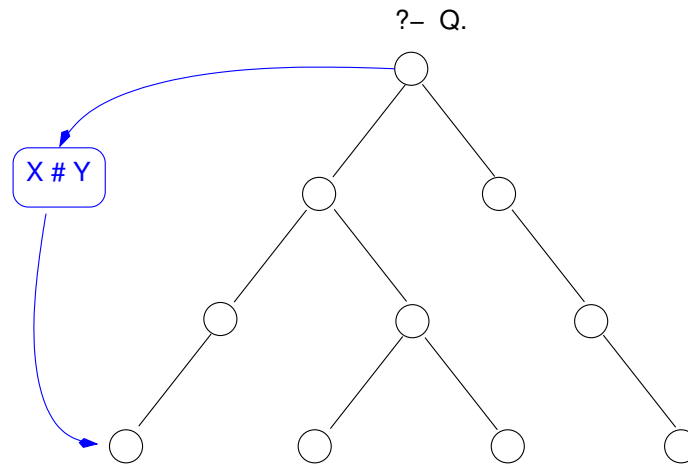
## Logic Programming :

- execution model is inflexible, and
- its relational nature discourages use of state information.

## Constraints add

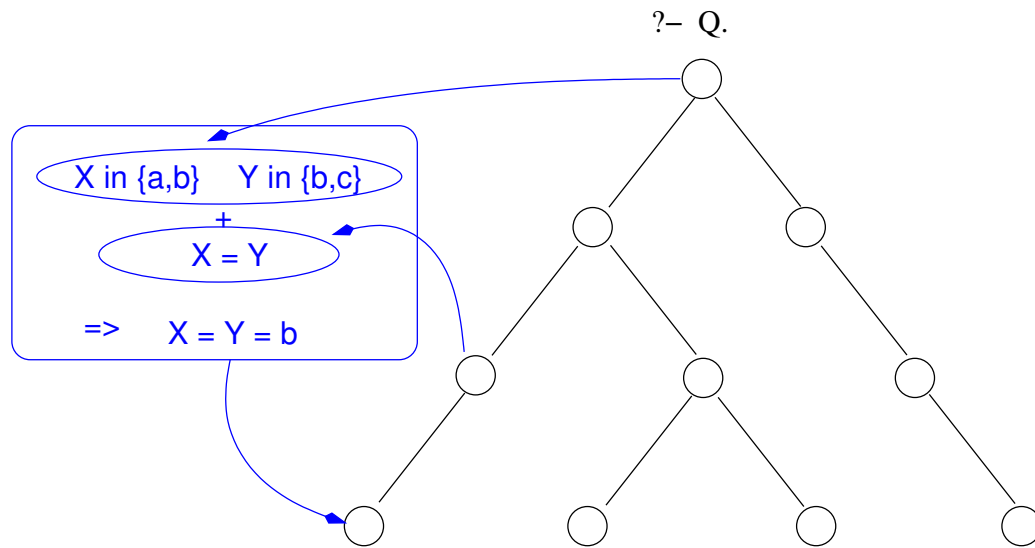
- specialised algorithms
- state information

# constraint store



- Logic Programming engine
- Constraint store interaction

# constraints inference



# finite domain distributions



For discrete probabilistic models  $\text{clp}(\text{pfd}(Y))$  extends the idea of finite domains to admit distributions.

from  $\text{clp}(\text{fd})$

$X \text{ in } \{a, b\}$  (i.e.  $X = a$  or  $X = b$ )

to  $\text{clp}(\text{pfd}(Y))$

$p(X = a) + p(X = b)$

# finite domain distributions



For discrete probabilistic models  $\text{clp}(\text{pfd}(Y))$  extends the idea of finite domains to admit distributions.

from  $\text{clp}(\text{fd})$

$$X \text{ in } \{a, b\} \quad (\text{i.e. } X = a \text{ or } X = b)$$

to  $\text{clp}(\text{pfd}(Y))$

$$[ p(X = a) + p(X = b) ] = 1$$

# constraint based integration



Execution, assembles the probabilistic model in the store according to program and query.

Dedicated algorithms can be used for probabilistic inference on the model present in the store.



# clp(pfd(Y))



For finite domain variable  $V$  in  $\{e_1, \dots, e_n\}$

and specific probabilistic inference algorithm  $Y$ ,  
clp(pfd(Y)) assumes

$$\psi_S(V) = \{(e_1, \pi_1), (e_2, \pi_2), \dots, (e_n, \pi_n)\}$$

We let  $p(e_i) = \pi_i$ .

Given a particular store and program:

probability of a query or predicate containing probabilistic variables is equal to the sum of product of probabilities for elements that satisfy the query.

## clp(pfd(Y)) example



For example, for program  $\mathcal{P}_1$ :

$lucky(iv, hd). lucky(v, hd). lucky(vi, hd).$

store  $\mathcal{S}_1$  with variables  $D$  and  $C$ , with

$$\psi_{\mathcal{S}_1}(D) = \{(i, 1/6), (ii, 1/6), (iii, 1/6), \\ (iv, 1/6), (v, 1/6), (vi, 1/6)\}$$

$$\psi_{\mathcal{S}_1}(C) = \{(hd, 1/2), (tl, 1/2)\}.$$

The probability of a lucky combination is

$$P_{\mathcal{S}_1}(lucky(D, C)) = 1/4.$$

# probability of predicates

- $\mathcal{S}$  - a constraint store.
- $e$  - vector of finite domain elements
- $E/e$  -  $E$  with variables replaced by  $e$ .

The probability of predicate  $E$  with respect to store  $\mathcal{S}$  is

$$P_{\mathcal{S}}(E) = \sum_{\substack{\forall e \\ \mathcal{S} \vdash E/e}} P_{\mathcal{S}}(e) = \sum_{\substack{\forall e \\ \mathcal{S} \vdash E/e}} \prod_i p(e_i)$$

# labelling



In clp(fd) systems labelling instantiates a group of variables to elements from their domains.

In clp(pfd(Y)) the probabilities can be used to guide labelling. For instance we have implemented

*label(Vars, mua, Prbs, Total)*

Selector *mua* approximates best-first algorithm which instantiates a group of variables to most likely combinations.

clp(pfd(c))



Probabilistic variables are declared with

$$V \sim \phi_V(Fd, Args)$$

e.g.  $Heat \sim finite\_geometric([l, m, h], [2])$

finite geometric distribution with deterioration factor is 2.  
In the absence of other information

$$\psi_{\{Heat\}}(Heat) = \{(l, 4/7)(m, 2/7), (h, 1/7)\}$$

Probability ascribing function  $\phi_V$  and finite domain  $Fd$  are kept separately.

# clp(pfd(c)) conditionals



Conditional  $C$

$$D_1 : \pi_1 \oplus \dots \oplus D_m : \pi_m \mid Q$$

Each  $D_i$  is a predicate and all should share a single probabilistic variable  $V$ .  $Q$  is a predicate not containing  $V$ , and

$$0 \leq \pi_i \leq 1, \sum_i \pi_i = 1$$

$V$ 's distribution is altered as a result of  $C$  being added to the store.

# conditional different-than



## Conditional different-than constraint

$$Y \neq Z$$

## Equivalent to

$$Y \neq T : \pi \oplus Y = T : (1 - \pi) \mid Z = T$$

# conditional example

— • • •

lucky( iv, hd). lucky( v, hd). lucky( vi, hd).

*Coin*  $\sim$  uniform([hd,tl])

*Die*  $\sim$  uniform([i,ii,iii,iv,v,vi])

constrained( P ) :-

Coin pin uniform( [hd,tl] ),

Die pin uniform( [i,ii,iii,iv,v,vi] ),

Die # v :: 1/3 ++ Die = v :: 2/3 \\ Coin = hd,

P is p( lucky(Die,Coin) ).

## Querying this program

?- constrained(Prb)

*Prb* = 2/5.



# Caesar's coding



Each letter is encrypted to a random letter. Words drawn from a dictionary are encrypted. Programs try to decode them. We compared a `clp(fd)` solution to `clp(pfd(c))` .

`clp(fd)` no probabilistic information, labelling in lexicographical order.

`clp(pfd(c))` distributions based on frequencies, labelling using *mua*.

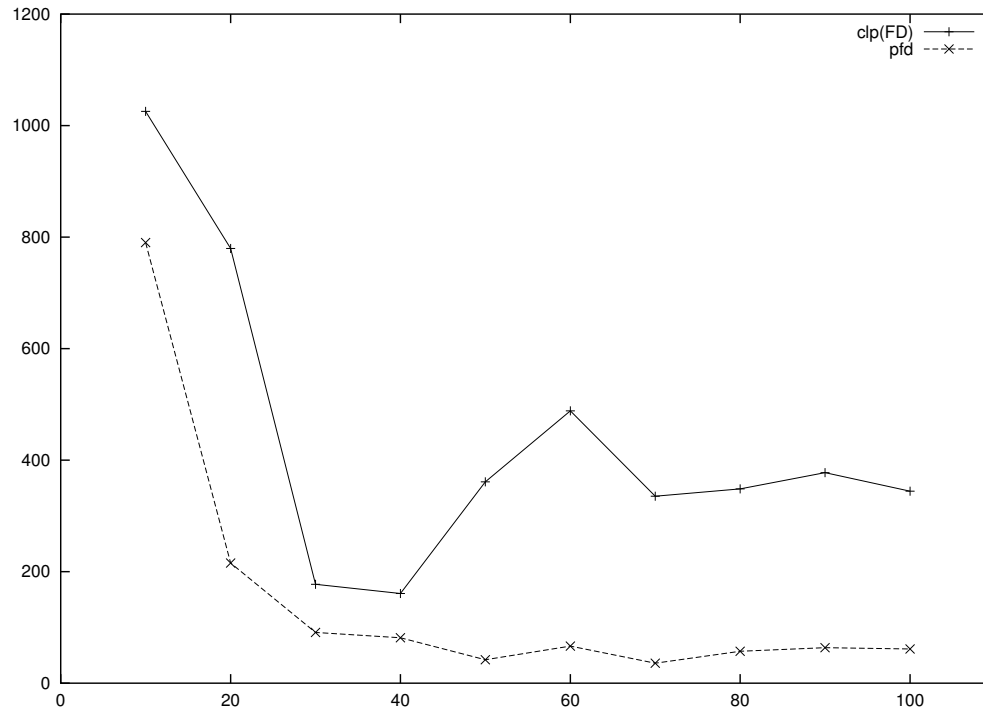
# proximity functions



- $X_i$  - variable for  $i$ th encoded letter
- $D_i$  - dictionary letter
- $\text{freq}()$  - frequency of letter

$$px(X_i, D_j) = \frac{1 / | \text{freq}(X_i) - \text{freq}(D_j) |}{\sum_k 1 / | \text{freq}(X_i) - \text{freq}(D_k) |}$$

# execution times



clp(pfd(c)) and clp(fd) on SICStus 3.8.6

# Monty Hall



Three curtains hiding a car and two goats.  
Contestant chooses an initial curtain.  
A close curtain opens to reveal a goat.  
Contestant is asked for their final choice.

What is the best strategy ?  
Stay or Switch ?

# Monty Hall solution



If probability of switching is  $Swt$ ,  
( $Swt = 0$  for strategy *Stay* and  $Swt = 1$  for *Switch*)  
then probability of win is  $P(\gamma) = \frac{1+Swt}{3}$ .

# Monty Hall in clp(pfd(c))



curtains( gamma, Swt, Prb ) :-

*Gift*  $\sim$  *uniform*([a, b, c]),

*First*  $\sim$  *uniform*([a, b, c]),

*Reveal*  $\sim$  *uniform*([a, b, c]),

*Second*  $\sim$  *uniform*([a, b, c]),

*Reveal*  $\neq$  *Gift*, *Reveal*  $\neq$  *First*, *Second*  $\neq$  *Reveal*,

*Second*  $\neq_{swt}$  *First* ,

*Prb* is **p**(*Second*=*Gift*).

# Strategy $\gamma$ Query



Querying this program

```
?- curtains(gamma, 1/2, Prb)  
Prb = 1/2.
```

# Strategy $\gamma$ Query

---

Querying this program

```
?- curtains(gamma, 1/2, Prb)  
Prb = 1/2.
```

```
?- curtains(gamma, 1, Prb)  
Prb = 2/3.
```



# Strategy $\gamma$ Query

---

Querying this program

?- curtains(gamma, 1/2, Prb)  
*Prb* = 1/2.

?- curtains(gamma, 1, Prb)  
*Prb* = 2/3.

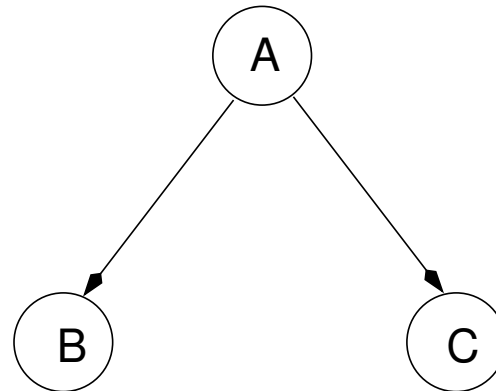
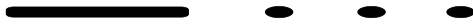
?- curtains(gamma, 0, Prb)  
*Prb* = 1/3.

clp(pfd(bn))



Other discrete probabilistic inference engines can be employed. For instance Bayesian Networks representation and inference.

# example BN



	A = y	A = n
B = y	0.80	0.10
B = n	0.20	0.90

	A = y	A = n
C = y	0.60	0.90
C = n	0.40	0.10

# clp(pfd(bn)) program



```
example_bn( A, B, C ) :-  
    cpt( A, [], [y,n] ),  
    cpt( B, [A], [ (y,y,0.8), (y,n,0.2),  
                  (n,y,0.1), (n,n,0.9) ] ),  
    cpt( C, [A], [ (y,y,0.6), (y,n,0.4),  
                  (n,y,0.9), (n,n,0.1) ] ) .
```

# program



```
example_bn( A, B, C ) :-  
    cpt( A, [], [y, n] ),  
    cpt( B, [A], [ (y, y, 0.8), (y, n, 0.2),  
                  (n, y, 0.1), (n, n, 0.9) ] ),  
    cpt( C, [A], [ (y, y, 0.6), (y, n, 0.4),  
                  (n, y, 0.9), (n, n, 0.1) ] ) .
```

```
?- example_bn( X, Y, Z ),  
    evidence( X, [ (y, 0.8), (n, 0.2) ],  
    Zy is p( Z = y ) .
```

# program

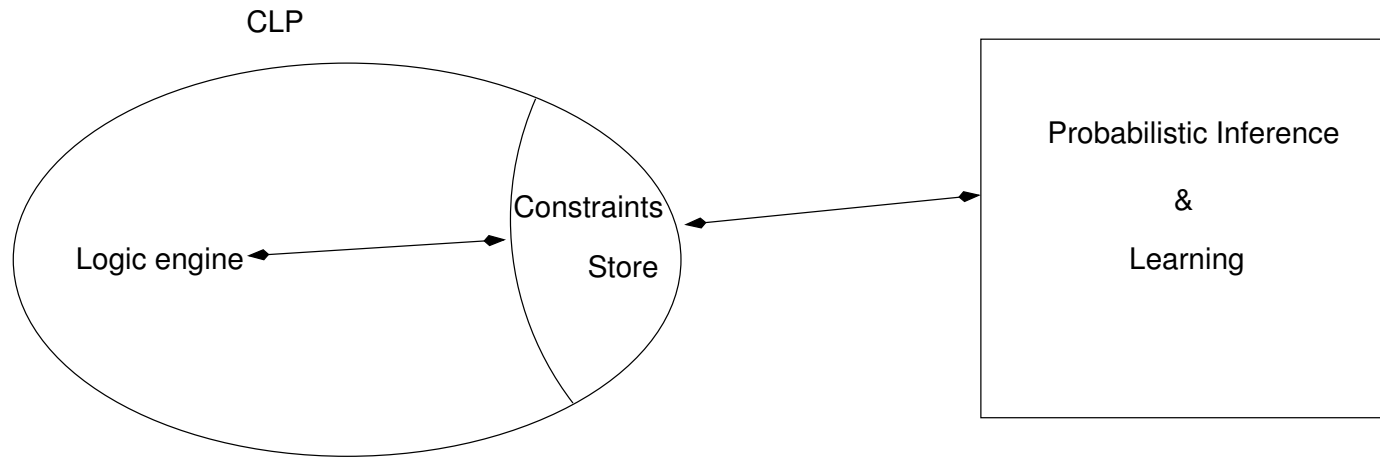


```
example_bn( A, B, C ) :-  
    cpt( A, [], [y, n] ),  
    cpt( B, [A], [ (y, y, 0.8), (y, n, 0.2),  
                  (n, y, 0.1), (n, n, 0.9) ] ),  
    cpt( C, [A], [ (y, y, 0.6), (y, n, 0.4),  
                  (n, y, 0.9), (n, n, 0.1) ] ) .
```

```
?- example_bn( X, Y, Z ),  
    evidence( X, [ (y, 0.8), (n, 0.2) ],  
    Zy is p( Z = y ) .
```

**Zy = 0.66**

# current inference scheme



## bottom line



Constraint LP based techniques can be used for frameworks that support probabilistic problem solving.

$\text{clp}(\text{pfd}(Y))$  can be used to take advantage of probabilistic information at an abstract level.



# bottom line

